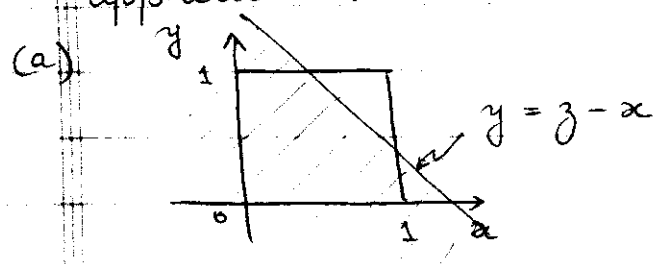


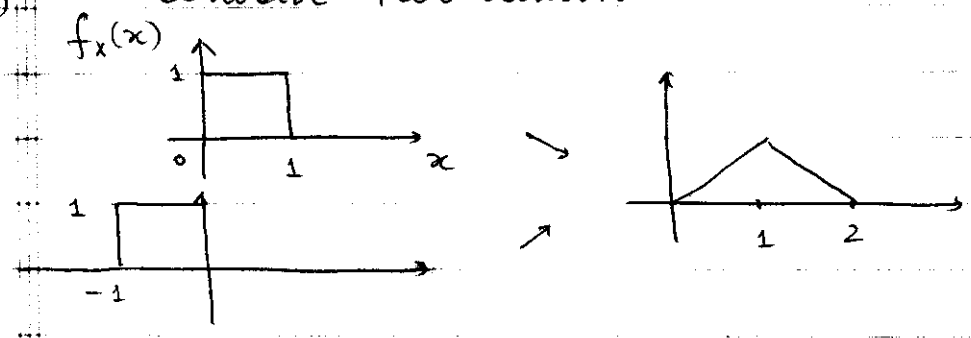
15

The density of  $Z$  can be evaluated using 2 approaches.

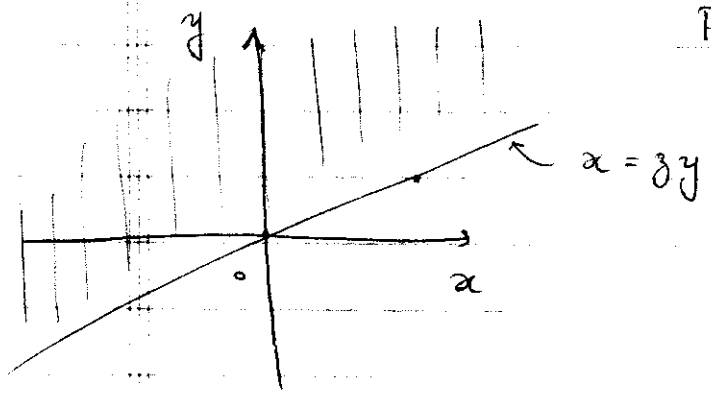


Integrate the region below  $x+y \leq z$  and differentiate.

(b) Convolve two densities:



ex. 2: Let  $Z = X/Y$



$$Pr[Z \leq z] = Pr[X/Y \leq z]$$

$$x = zy$$

$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{X,Y}(x,y) dx dy$$

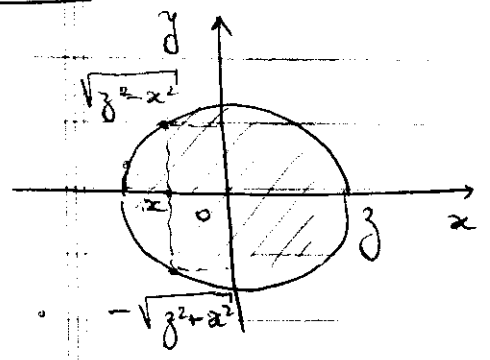
"x"  $x/z$  "y"

( $z > 0$ )

And the density of  $Z$  is

$$f_z(z) = \frac{1}{z^2} \int_{-\infty}^{+\infty} f_{X,Y}\left(x, \frac{x}{z}\right) x \cdot dx$$

ex. 3: Let  $Z = \sqrt{X^2 + Y^2}$



$$P_z(z) = Pr[\sqrt{X^2 + Y^2} \leq z] = Pr[X^2 + Y^2 \leq z^2]$$

$$= \int_{-z}^z \int_{-\sqrt{z^2 - x^2}}^{\sqrt{z^2 - x^2}} f_{X,Y}(x,y) dy dx$$

16

Let  $X \sim N(0, 1)$ ,  
 $Y \sim N(0, 1)$ ,

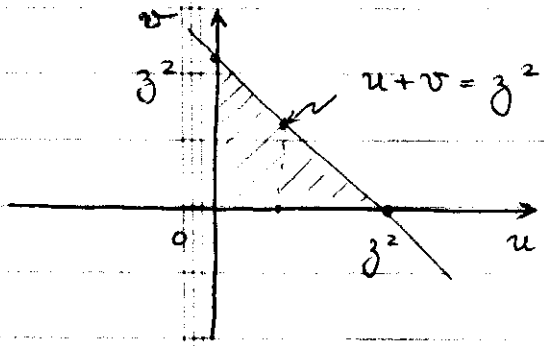
$X \perp\!\!\!\perp Y$   
 $\Rightarrow \boxed{U \perp\!\!\!\perp V}$

A solution:

Let  $U = X^2$  and  
 $V = Y^2$ , then  
 $\Pr\{U+V \leq z^2\}$

Recall,

$$\begin{aligned}
 P_U(u) &= \Pr[V \leq u] \\
 &= \Pr[X^2 \leq u] = \Pr[-\sqrt{u} \leq X \leq \sqrt{u}] \\
 &= \int_{-\sqrt{u}}^{\sqrt{u}} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \\
 f_U(u) &= \frac{1}{\sqrt{2\pi u}} e^{-u/2} \cdot \mathbb{I}_{\{u \geq 0\}} \leftarrow (x^2 \text{ with one degree of freedom})
 \end{aligned}$$



Hard!

$$\begin{aligned}
 &\Pr\{U+V \leq z^2\} \\
 &= \int_0^{z^2} \int_0^{z^2-u} f_{U,V}(u,v) du dv \\
 &\quad \underbrace{f_U(u) \cdot f_V(v)}_{U \perp\!\!\!\perp V} \\
 &= \int_0^{z^2} \frac{1}{\sqrt{2\pi u}} e^{-u/2} \int_0^{z^2-u} \frac{1}{\sqrt{2\pi v}} e^{-v/2} dv du
 \end{aligned}$$

Statement: Sum of independent central  $X^2$  RVs is a  $X^2$  RV with "sum" of degrees of freedom.

Thus,

$$W = X + Y \sim \frac{e^{-w/2}}{2} \cdot \mathbb{I}_{\{w \geq 0\}}$$

Then,

$$P_Z(z) = \Pr[W \leq z^2] = \frac{1}{2} \int_0^{z^2} e^{-w/2} dw$$

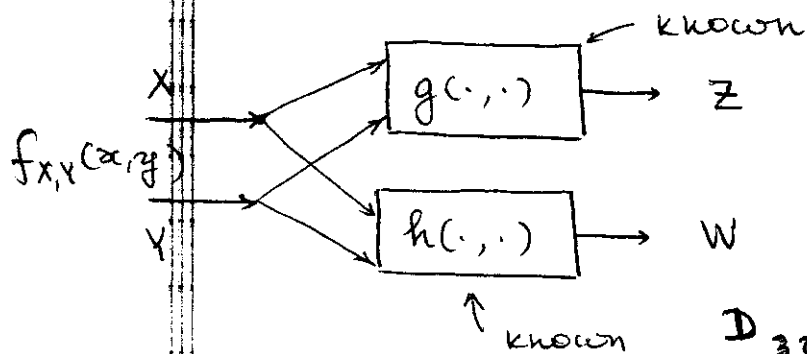
$$f_Z(z) = \frac{1}{2} \cdot 2z e^{-z^2/2} \mathbb{I}_{\{z \geq 0\}}$$

$$= z \cdot e^{-z^2/2} \cdot \mathbb{I}_{\{z \geq 0\}} \sim \text{Rayleigh distributed RV.}$$

(17)

## Two Functions of Two RVs

Let  $X$  and  $Y$  be distributed as  $f_{X,Y}(x,y)$



Find: joint cdf and pdf of the pair  $(Z,W)$ .

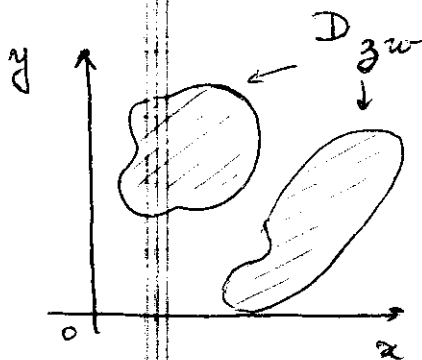
1. Find equivalent events

$$D_{zw} = \{(x,y) : g(x,y) \leq z, h(x,y) \leq w\}$$

$$\Pr [Z \leq z, W \leq w]$$

$$= \Pr [g(x,y) \leq z, h(x,y) \leq w]$$

$$= \Pr [(x,y) \in D_{zw}]$$



ex.

Let  $W = X + Y$

$Z = X/Y$

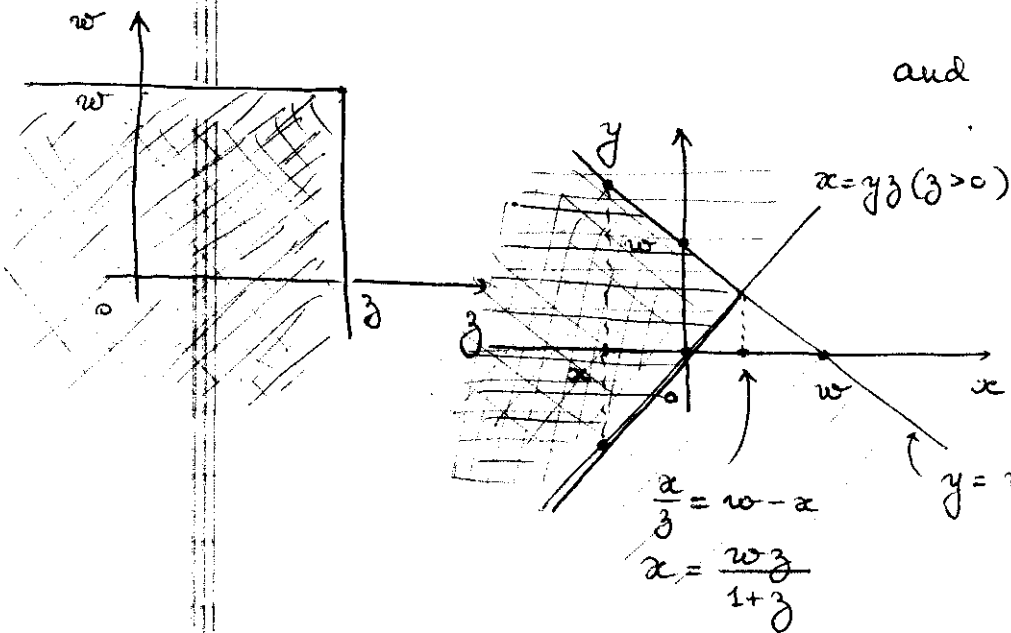
and  $f_{X,Y}$  be given.

$$\Pr [Z \leq z, W \leq w]$$

$$= \Pr [X/Y \leq z, X+Y \leq w]$$

$$= \int_{-\infty}^{\frac{wz}{1+z}} \int_{\frac{x}{z}}^{w-x} f_{X,Y}(x,y) dy dx$$

"x"                      "y"



## Joint Density :

Let  $Z = g(X, Y)$  and  $W = h(X, Y)$   
 $\quad \quad \quad \uparrow$  known  $\quad \quad \quad \uparrow$  known.

Let  $f_{X,Y}(x, y)$  is given.

Theorem: To find  $f_{Z,W}(z, w)$  we solve the system of equations:

$$\begin{cases} g(x, y) = z \\ h(x, y) = w \end{cases} \quad (1)$$

Let  $\{(x_n, y_n)\}$  be real roots of the system.

Then

$$f_{Z,W}(z, w) = \frac{f_{X,Y}(x_1, y_1)}{|J(x_1, y_1)|} + \dots + \frac{f_{X,Y}(x_n, y_n)}{|J(x_n, y_n)|} + \dots$$

where

$$J(x, y) = \det \begin{bmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{bmatrix} = \frac{1}{\det \begin{bmatrix} \frac{\partial x}{\partial z} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial z} & \frac{\partial y}{\partial w} \end{bmatrix}}$$

is the Jacobian of the transformation (1).

ex.

(Rotation)

$$\begin{aligned} \text{Let } Z &= X \cos \varphi + Y \sin \varphi \\ W &= -X \sin \varphi + Y \cos \varphi \end{aligned}$$

$$\begin{bmatrix} Z \\ W \end{bmatrix} = \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} \cdot \begin{bmatrix} X \\ Y \end{bmatrix}$$

orthogonal matrix  
(rotation)

$$\begin{aligned} QQ^T &= I \\ Q^T &= Q^{-1} \end{aligned}$$

$$\begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix}^{-1} \cdot \begin{bmatrix} Z \\ W \end{bmatrix}$$

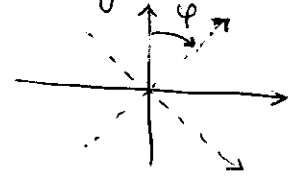
$$\begin{bmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{bmatrix}$$

Using Theorem,

$$f_{Z,W}(z,w) = f_{X,Y}(z \cos \varphi - w \sin \varphi, z \sin \varphi + w \cos \varphi)$$

where  $|J| = 1$ .

Thus, if two RVs are rotated by an angle  $\varphi$ , their pdf is rotated by the same angle in the opposite direction.



ex. (Polar Representation)

$$\text{Let } R = \sqrt{X^2 + Y^2} \quad \text{and} \quad \Phi = \tan^{-1} Y/X$$

$$r \geq 0, \quad -\pi < \varphi \leq \pi$$

Consider the system of equations:

$$\begin{cases} r = \sqrt{x^2 + y^2} \\ \varphi = \tan^{-1} y/x \end{cases} \Rightarrow \begin{cases} x = r \cos \varphi \\ y = r \sin \varphi \\ r > 0 \end{cases}$$

The Jacobian is

$$J(x,y) = \begin{bmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{bmatrix}^{-1} = \frac{1}{r}$$

Then

$$f_{R,\Phi}(r,\varphi) = r f_{X,Y}(r \cos \varphi, r \sin \varphi), \quad r > 0$$

$$0, \quad \text{if } r < 0.$$

Auxiliary Variables:

Finding a density of mapped RVs  $Z = g(X,Y)$  sometime can be simplified <sup>(by introducing)</sup> an auxiliary variable  $W$  (conveniently selected). The density of  $Z$  is then obtained by integrating  $W$  out.

ex.

$$Z = aX + bY$$

The auxiliary RV could be  $W = Y$ .

# Functions of Multiple RVs

Similar to the case of single RV, we can define partial characterizations of a vector R.V.

1. Consider two RVs  $X$  and  $Y$  with joint pdf  $f_{X,Y}(x,y)$ . Let  $Z = g(X,Y)$

known, deterministic

How to find  $E[Z]$ ?

There are two options: (1) find  $f_Z(z)$  and then find  $E[Z]$ ; (2)

$$E[Z] = E[g(X,Y)] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x,y) f_{X,Y}(x,y) dx dy$$

ex. Let  $X$  and  $Y$  be exponential ( $\lambda$ ) and  $X \perp\!\!\!\perp Y$ . Let  $M = \frac{X+Y}{2}$ .

Find:  $E[M]$ ?

$$E[X] = \frac{1}{\lambda}$$

$$\text{Then } E[M] = E\left[\frac{X+Y}{2}\right]$$

$$= \frac{1}{2} E[X] + \frac{1}{2} E[Y]$$

linearity  $\rightarrow$   
$$= \frac{1}{\lambda}$$

$$\text{Let } V = \frac{1}{2} (X-M)^2 + \frac{1}{2} (Y-M)^2$$

Find:  $E[V]$ ?

$$V = \frac{(X-Y)^2}{4} \Rightarrow E[V] = \frac{1}{4} E[X^2] + \frac{1}{4} E[Y^2]$$

$$- \frac{1}{2} E[XY]$$

Requires new definition

Recall:  $\text{var}(X) = \frac{1}{\lambda^2}$

$$\text{Then } E[X^2] = \frac{1}{\lambda^2} + \frac{1}{\lambda^2} = \frac{2}{\lambda^2}$$

From here:

$$E[V] = \frac{1}{\lambda^2} - \frac{1}{2} E[XY]$$

Note:  $M$  and  $V$  are known as sample mean and sample variance.

2. Covariance is the 2nd order statistic.

Analogy can be drawn with variance of a RV. It can be used as an average measure of information that one central RV contains about some other central RV.

Defn. Covariance,  $\text{cov}(X, Y)$  of two RVs  $X$  and  $Y$  is defined as

$$\begin{aligned} \text{cov}(X, Y) &\triangleq E[(X - E[X])(Y - E[Y])] \\ &= E[XY - E[X]Y - XE[Y] + E[X]E[Y]] \end{aligned}$$

expand

$$\begin{aligned} &= E[XY] - E[X]E[Y] - E[X]E[Y] + E[X]E[Y] \\ &= E[XY] - E[X]E[Y] \end{aligned}$$

linearity

Thus,

$$\text{cov}(X, Y) \triangleq E[XY] - E[X]E[Y]$$

3.

Correlation Coefficient (normalized covariance)

If  $Y$  is a fuct. of  $X$ , then  $\text{var}(X)$  will implicitly appear in the expression for  $\text{cov}(X, Y)$ .

$$\rho_{X,Y} = \frac{\text{cov}(X,Y)}{\sqrt{\text{var}(X)\text{var}(Y)}}$$

$$|\rho_{X,Y}| \leq 1 \quad \text{and thus} \quad |\text{cov}(X,Y)| \leq \sqrt{\text{var}(X)\text{var}(Y)}$$

Defn.

Two RVs  $X$  and  $Y$  are uncorrelated if

$$\text{cov}(X,Y) = 0,$$

$$\rho_{X,Y} = 0, \quad \text{or}$$

$$E[XY] = E[X]E[Y]$$

Defn.

Two RVs are orthogonal if

$$E[XY] = 0$$

$$(X \perp Y)$$

Back to the example:

$$E[XY] = E[X]E[Y]$$

↑ independent

$$= \frac{1}{\lambda^2}$$

$$\Rightarrow E[V] = \frac{1}{2} \cdot \frac{1}{\lambda^2}$$

Theorem: If the two RVs,  $X$  and  $Y$ , are independent, then  $X$  and  $Y$  are uncorrelated, that is,

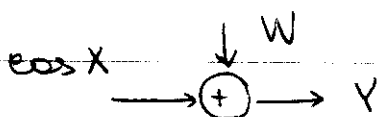
$$f_{X,Y}(x,y) = f_X(x)f_Y(y)$$

$$\Rightarrow E[XY] = E[X]E[Y]$$

The converse is not true,

↯

ex.



assume  $X$  and  $W$  have  $f_{X,W}(x,w)$

Find:  $E[Y]$ ,  $\text{cov}(X,Y)$

$$Y = \cos X + W$$

$$E[Y] = E[\cos X] + E[W]$$

↑ linear operator

$$\text{cov}(X,Y) = E[XY] - E[X]E[Y]$$

$$= E[X \cdot (\cos X + W)] - E[X] \cdot (E[\cos X] + E[W])$$

$$= E[X \cos X] + E[X \cdot W] - E[X] \cdot E[\cos X] - E[X]E[W]$$

$$= E[X \cos X] - E[X] \cdot E[\cos X]$$

$X \perp W$  (uncorrelated is sufficient)

### 4. Joint Moments:

The joint  $(k, l)$ th moments of two RVs  $X$  and  $Y$  is defined as:

$$m_{k,l} \triangleq E[X^k Y^l] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} x^k y^l f_{X,Y}(x,y) dx dy$$

also called joint moment of order  $(k+l)$ .

The  $(k, l)$ th joint central moment of RVs  $X$  and  $Y$  is defined as:

$$\begin{aligned} \mu_{k,l} &\triangleq E[(X - E[X])^k (Y - E[Y])^l] \\ &= \int \int (x - E[X])^k (y - E[Y])^l f_{X,Y}(x,y) dx dy \end{aligned}$$

Clearly,

$$\mu_{10} = \mu_{01} = 0$$

$$\begin{aligned} \mu_{11} &= \text{cov}(X, Y), & \mu_{20} &= \text{var}(X) \\ \mu_{02} &= \text{var}(Y), & & \dots \end{aligned}$$

Comment:  $\left. \begin{matrix} f_{X,Y}(x,y) \\ F_{X,Y}(x,y) \end{matrix} \right\}$  complete characterizations of the pair  $(X, Y)$ .

However, in many applications only the 1st and 2nd order moments are used.  
(ex. bounds)

### 5. Joint Characteristic Function

Let  $X$  and  $Y$  be two RVs with the joint pdf  $f_{X,Y}(x,y)$ . The joint characteristic function of  $X$  and  $Y$  is defined as

$$M_{X,Y}(ju, jv) \triangleq E[e^{j(uX + vY)}]$$

$$= \iint_{-\infty - \infty}^{+\infty + \infty} e^{jux + jvy} f_{X,Y}(x,y) dx dy$$

The inverse equation is given by:

$$f_{X,Y}(x,y) = \frac{1}{(2\pi)^2} \iint_{-\infty - \infty}^{+\infty + \infty} M_{X,Y}(ju, jv) \cdot e^{-jux - jvy} du dv$$

(a) The marginal characteristic functions are:

$$M_X(ju) = M_{X,Y}(ju, jv) \Big|_{v=0}$$

$$M_Y(jv) = M_{X,Y}(ju, jv) \Big|_{u=0}$$

(b) Independence and Convolution:

if  $X \perp Y$ , then  $Z = X + Y$  has the following pdf:

$$f_Z(z) = \int_{-\infty}^{+\infty} f_X(x) \cdot f_Y(z-x) dx$$

Then the characteristic function of  $Z$  is:

$$E[e^{jvZ}] = E[e^{jv(X+Y)}]$$

$$= E[e^{jvX}] \cdot E[e^{jvY}] = M_X(jv) \cdot M_Y(jv)$$

↑  
independence,  $X \perp Y$

(c) Moments:

To obtain the joint moment of the order  $(k+l)$ :

$$m_{k,l} = \frac{\partial^k}{\partial (ju)^k} \frac{\partial^l}{\partial (jv)^l} M_{X,Y}(ju, jv) \Big|_{\substack{u=0 \\ v=0}} = E[X^k Y^l]$$